

# **DXOMARK ROBOTIC STEREOVISION MODULE EVALUATION REPORT**

**--Sample report--**

8 bits image sensor and lens evaluation

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|                   |                   |
|-------------------|-------------------|
| Chip total size   | 165x40x35 mm      |
| Pixel size        | 3 μm              |
| Max resolution    | 1920 x 1080       |
| Full frame rate   | 60 fps            |
| Lens FOV (H/V/D)  | 110° / 80° / 120° |
| Baseline distance | 120 mm            |
| Shutter control   | Global shutter    |

### Testing Conditions

|               |          |
|---------------|----------|
| Mode sensor   | Default  |
| Frame Grabber | vRGB-E2s |
| SW version    | 13.12    |
| Output        | RGB      |

|                    |             |
|--------------------|-------------|
| Framerate          | 30 fps      |
| Image resolution   | 1920 x 1080 |
| Exposure time (ms) | 16          |
| Gain               | 1           |

### Overall Performance

|                    |                        |
|--------------------|------------------------|
| DR (SNR1 40°C)     | 20 dB                  |
| Saturation (D65)   | 1200 cd/m <sup>2</sup> |
| Dark (40°C)        | 26e-                   |
| Full Well Capacity | 847860e-               |
| Dark flatness      | 3.1                    |

|                       |       |
|-----------------------|-------|
| DR P2020              | 17 dB |
| Noise Autocorrelation | 3 x 3 |
|                       |       |
|                       |       |
|                       |       |

## Measurement description

### 1. SFR / Resolution

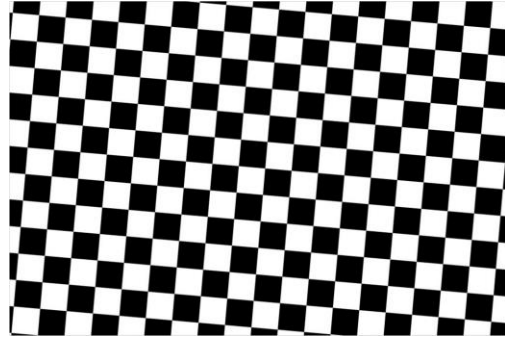
#### Standard compliance

The SFR measurement is fully compliant with the standard ISO 12233.

#### Metrics details

The SFR is computed in a linearized image.

#### Measurement setup specifications



SFR measurement compensate the target printer MTF. The target MTF is measured compared to a true cutter target, and it is then taken into account during the camera MTF measurement.

## Measurement description

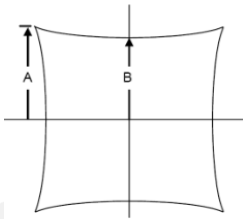
### 2. Distortion and lateral chromatic aberration

#### Standard compliance

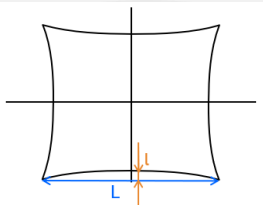
The lens distortion measurement is fully compliant with the standard ISO 17850, and the chromatic aberration measurement is fully compliant with the ISO 19084 standard.

#### Metrics details

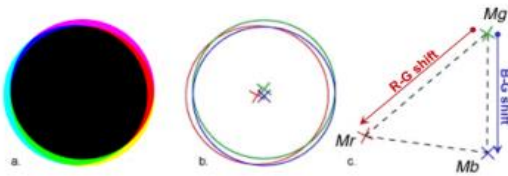
TV distortion:  $100 \cdot \frac{A-B}{B}$ , with A and B defined on the following figure:



Geometric distortion:  $100 \cdot \frac{l}{L}$ , with l and L defined on the following figure:



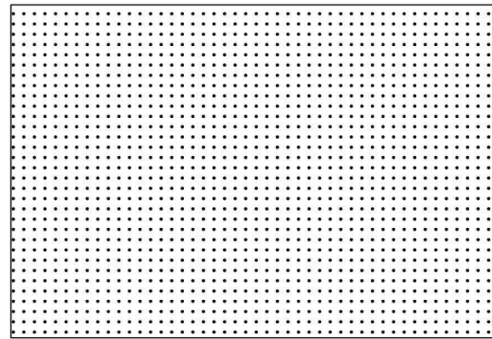
Chromatic aberrations: shift between R and G, and between B and G:



Definition of chromatic aberration profiles

#### Measurement setup specifications

DOT Chart:



## Measurement description

### 3. Vignetting/Color Lens Shading

#### Standard compliance

The Vignetting/Color Lens Shading measurement is fully compliant with the standard ISO 17957.

#### Metrics details

Vignetting Profile: gray level value divided by the gray level value at the vignetting center, for each radial field position and each color channel.

Color vignetting: each channel vignetting divided by green (average of G1 and G2 channels) vignetting.

#### Measurement setup specifications

Integrating sphere RO-LIS-3CR80 with 5100K.

## Measurement description

### 4. Flicker Mitigation

#### Standard compliance

The flicker mitigation measurement is fully compliant with the standard draft IEEE/P2020 published in dec 2022.

#### Metrics details

The Flicker Modulation Index (FMI) is defined as:

$$FMI = 100 \times \frac{s_{max} - s_{min}}{s_{max} + s_{min}}$$

Where  $s_{max}$  and  $s_{min}$  are respectively the maximum and minimum values of the measured signal for the considered time-range of the video.

The Flicker Detection Index (FDI) is defined as:

$$FDI = P \left[ \frac{s(t) - s_{off}}{s_{off}} \geq th \right]$$

Where:

- $P$  is the probability.
- $s(t)$  is the measured signal.
- $s_{off}$  is the measured signal when the PWM signal is off.
- $th$  is a minimum threshold above which the LED is considered visible.

The Modulation Mitigation Probability (MMP) is defined as:

$$MMP = P[\overline{s_{ref}}(1 - \delta) < s(t) < \overline{s_{ref}}(1 + \delta)]$$

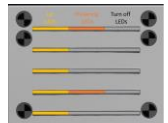
Where:

- $P$  is the probability.
- $s(t)$  is the measured signal.
- $\overline{s_{ref}}$  is the expected signal.
- $\delta$  is a parameter defining the lower and upper bounds of the signal interval in which the device is considered as able to successfully mitigate the LED flickering.

#### Measurement setup specifications

The flickering is generated by the DXOMARK Led Universal Timer.

This device provides a light modulated by a square signal with frequency in range [50, 2000] Hz, adjustable duty cycle, phase and intensity.





## Measurement description

### 5. Dynamic Range

#### Standard compliance

The Dynamic Range measurement is fully compliant with the standard draft IEEE/P2020 published in dec 2022.

#### Metrics details

The CNR (Contrast to Noise Ratio) between a pair of ROIs A and B is defined as:

$$CNR(A, B) = \frac{S_A - S_B}{\sqrt{\sigma_A^2 + \sigma_B^2}}$$

Where:

- $S_A$  and  $S_B$  are respectively the mean signals of the ROIs A and B
- $\sigma_A$  and  $\sigma_B$  are respectively the standard deviations of the ROIs A and B

The TCG (Tonal Contrast Gain) is the transfer function between the scene contrast and the image contrast:

$$TCG(A, B) = \frac{\log_2 \left( \frac{L_{A,Image}}{L_{B,Image}} \right)}{\log_2 \left( \frac{L_{A,Scene}}{L_{B,Scene}} \right)}$$

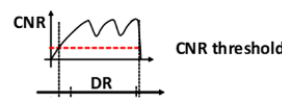
Where:

- $L_{A,Image}$  and  $L_{B,Image}$  are the mean signals the ROIs A and B in the image
- $L_{A,Scene}$  and  $L_{B,Scene}$  are the luminance values the ROIs A and B in the scene.

Dynamic Range is measured as CDR (Contrast Detection Ratio):

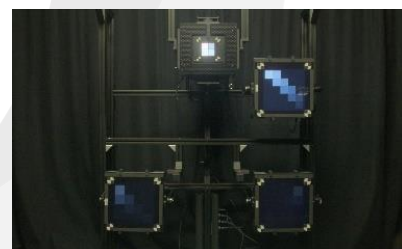
$$CDR_{dB} = 20 \log_{10} \left( \frac{L_{max} [CNR > 1]}{L_{min} [CNR > 1]} \right)$$

Where  $L_{max} [CNR > 1]$  and  $L_{min} [CNR > 1]$  are respectively the maximum and the minimum luminance values that verify  $CNR > 1$ .

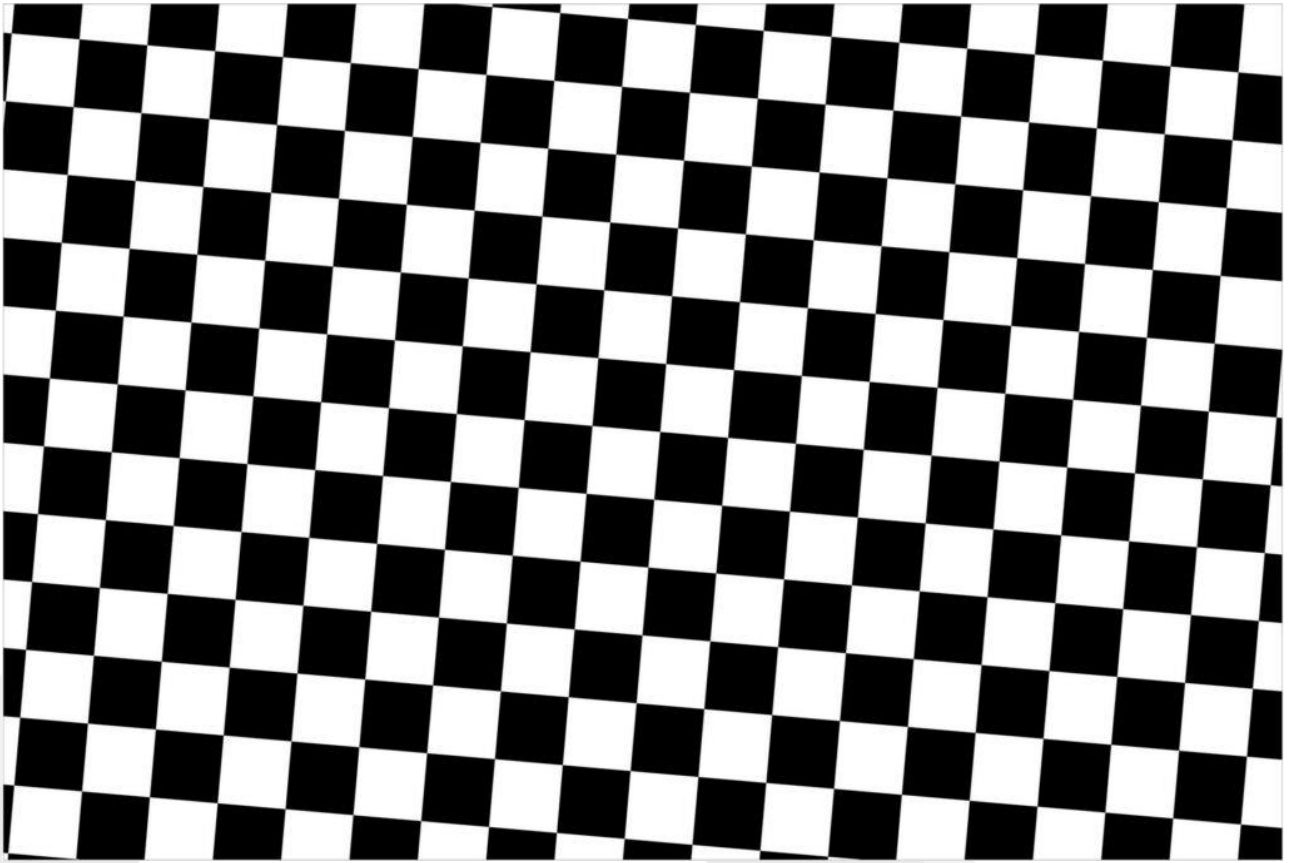


#### Measurement setup specifications

The dynamic range setup is an assembly of 4 light panels, delivering 25 patches that can reach at least 150 dB dynamic.



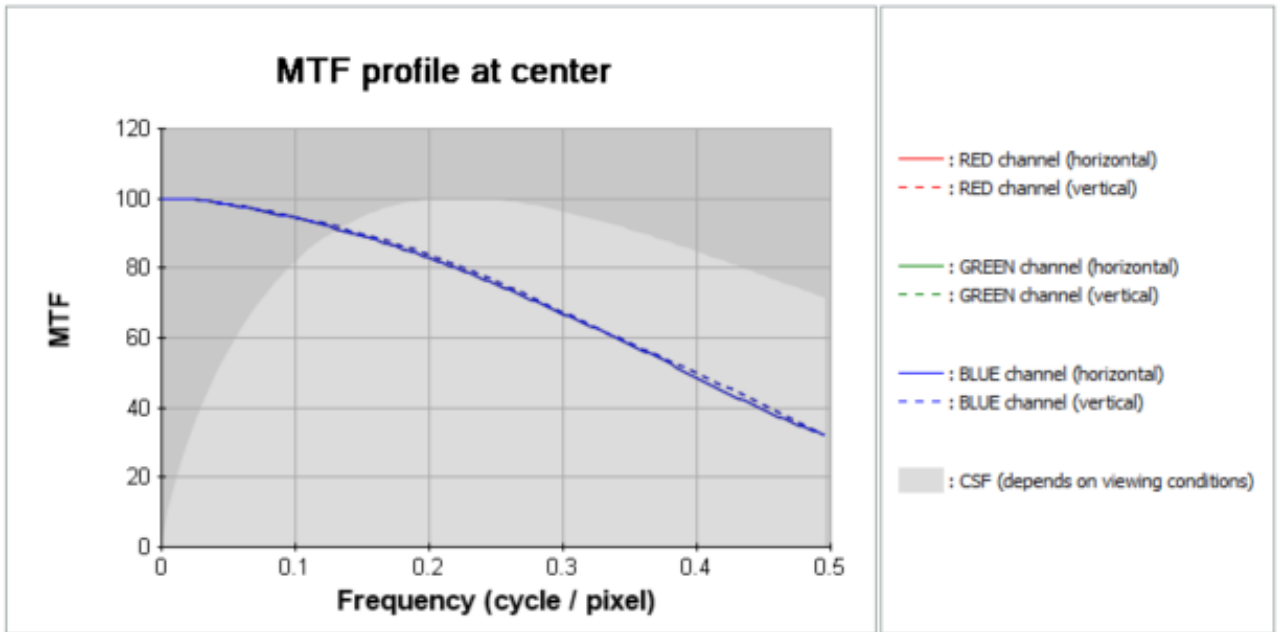
The measurement is performed for different positions in the field of view of the device.



• **Measurement conditions:**

- Illumination: D65 360lux
- Through focus to find the best sharpness in the center
- DUT to chart distance: 7m
- Number of images averaged: 30
- Viewing condition for acutance computation:
  - Distance: 600mm
  - Pixel pitch: 0.254mm

- MTF at 7 m, chart illumination : D65 360 lux



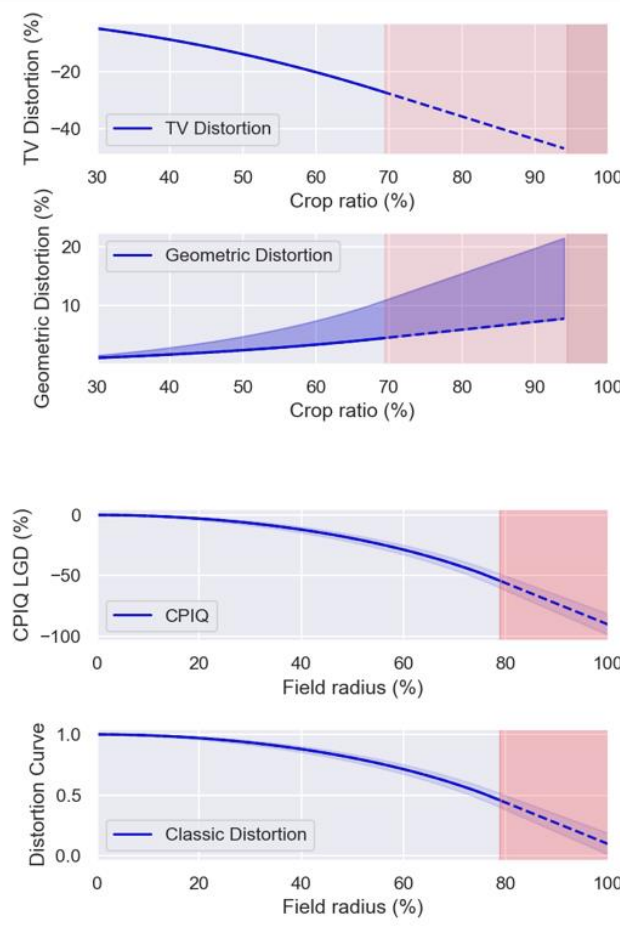
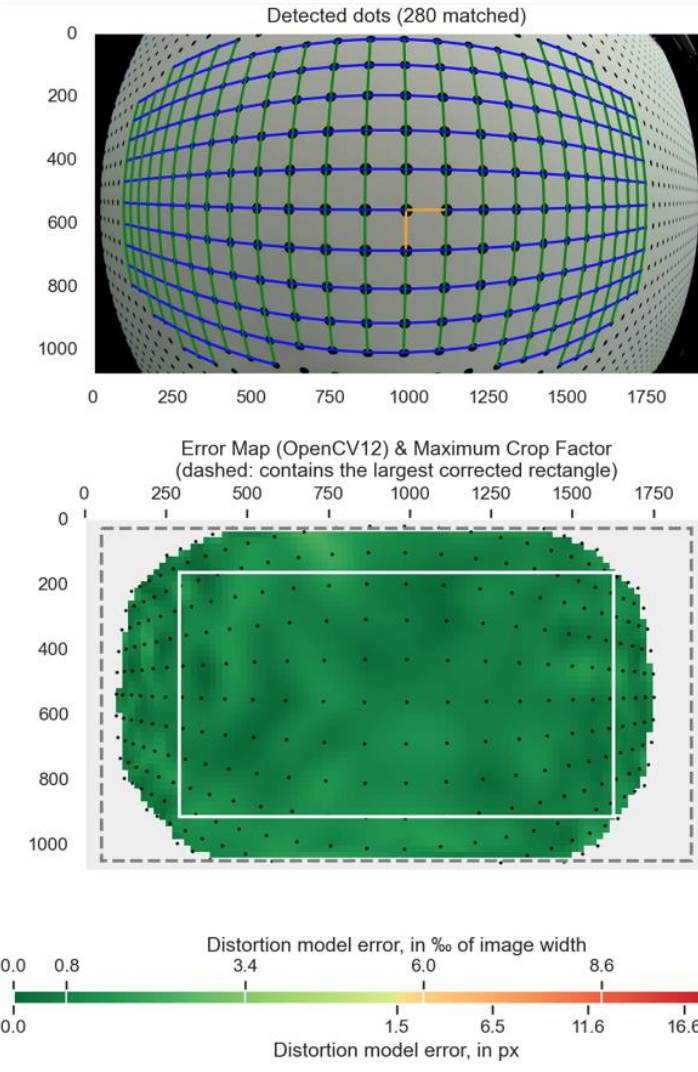
This table contains the averaged values (H and V) of the MTF for the green channel

|                    | Acutance | Limiting resolution (MTF 10%)   | MTF 50%                         | Ringing |
|--------------------|----------|---------------------------------|---------------------------------|---------|
|                    |          | cycles/pixel (lp/mm 24x36mm eq) | cycles/pixel (lp/mm 24x36mm eq) |         |
| Center             | 0.39     | 0.50 (14.25)                    | 0.40 (11.33)                    | 0%      |
| All corners (mean) | 0.40     | 0.50 (14.25)                    | 0.41 (11.56)                    | 0%      |

**Details:**

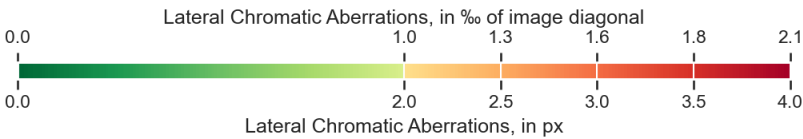
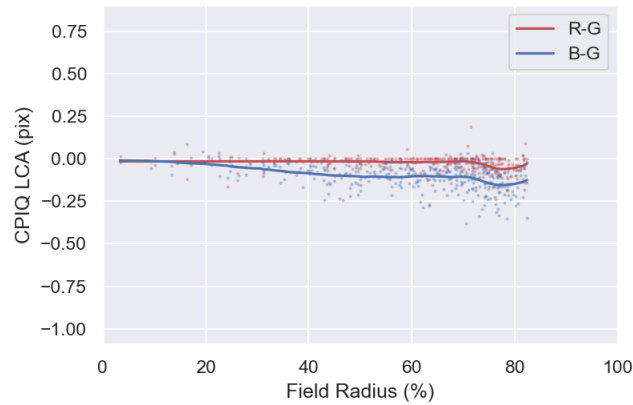
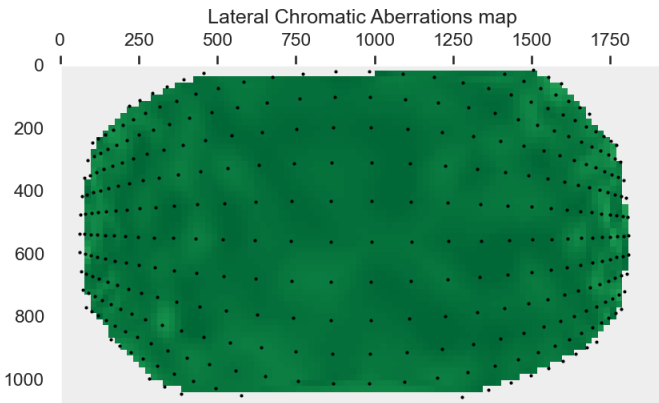
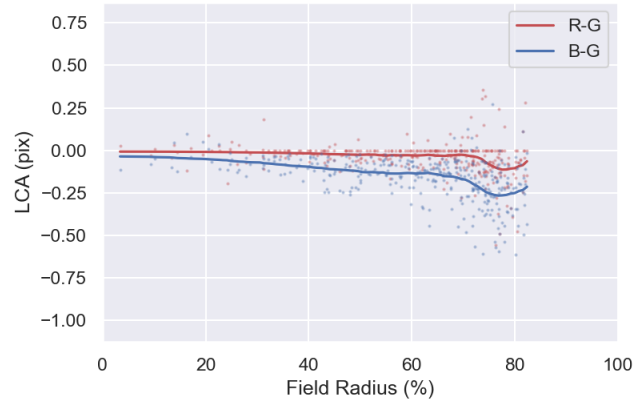
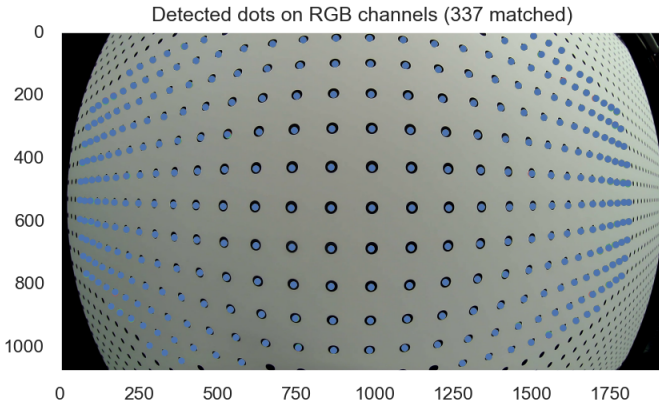
Conversion factor between cycles/pixels and cycles/degrees for viewing conditions [ 03 - Professional Photo Print (closer) ]

**Pixels/Degree** 17.933



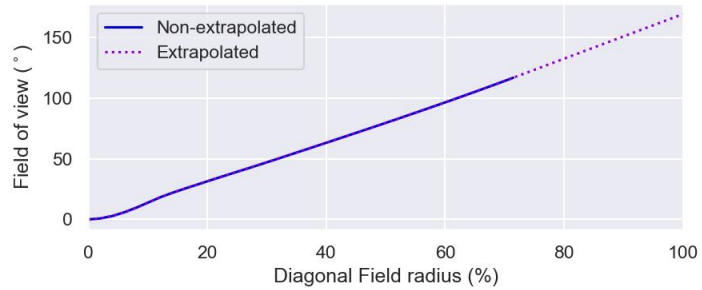
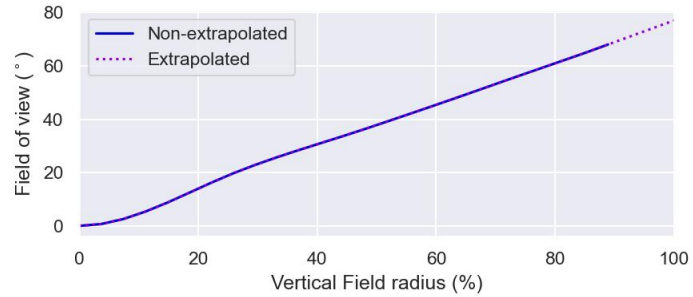
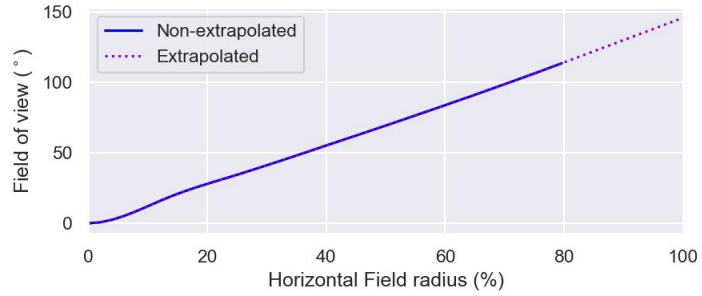
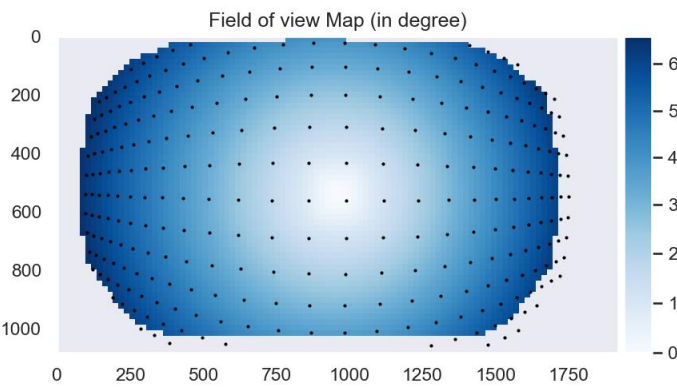
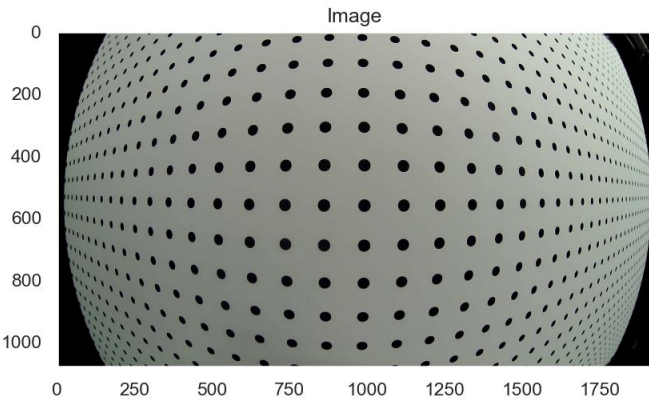
|                            | Results | Results (extrapolated) |
|----------------------------|---------|------------------------|
| TV Distortion              | -46.83% | -27.27%                |
| Geometric Distortion (avg) | +7.81%  | +4.55%                 |
| Geometric Distortion (Max) | +21.48% | +11.00%                |
| CPIQ LGD (Max)             | -98.73% | -59.81%                |
| CPIQ LGD (JND)             | -15.17% | -15.17%                |

Good fitting of the distortion model (small reprojection error)



|                        |          |
|------------------------|----------|
| CPIQ Max LCA (Pixels)  | -0.15 px |
| CPIQ Max LCA (Percent) | -0.01 %  |
| CPIQ Max LCA (JND)     | 0.00     |

**Chromatic Aberrations are negligible (less than 1 pixel in the full measurement area)**

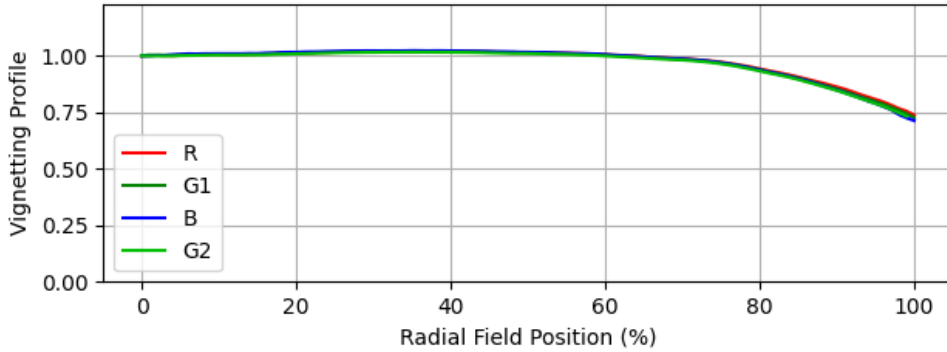


|                  | H. FoV  | V. FoV | D. FoV  |
|------------------|---------|--------|---------|
| Non-extrapolated | 113.41° | 67.98° | 116.96° |
| Extrapolated     | 145.64° | 77.01° | 169.55° |
|                  | Tilt    | Pan    |         |
| Orthofrontality  | 2.5°    | 0.68°  |         |

|               | Horizontal | Vertical | Diagonal |
|---------------|------------|----------|----------|
| Field of View | 145°       | 77°      | 170°     |

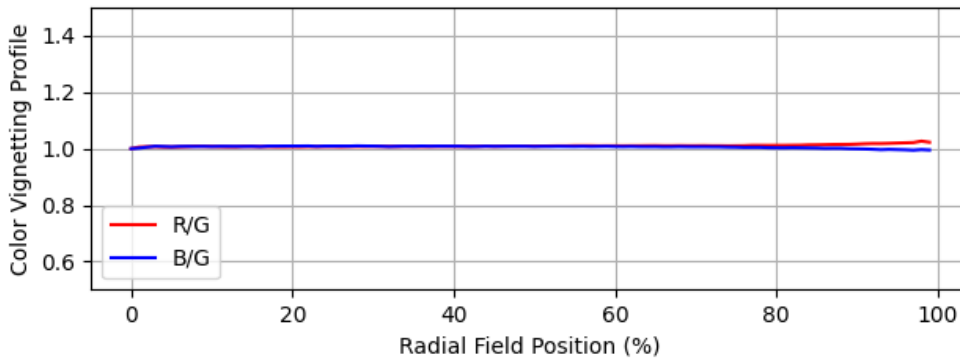
Fisheye lens: The field of view is linear with the field radius

Vignetting



|                   | R      | G1     | B      | G2     |
|-------------------|--------|--------|--------|--------|
| Max Attenuation   | 24.5 % | 25.6 % | 27.5 % | 26.8 % |
| Max Amplification | 2.0 %  | 2.0 %  | 2.3 %  | 1.6 %  |

Color Lens Shading



|                   | R     | B     |
|-------------------|-------|-------|
| Max Attenuation   | 0.8 % | 2.3 % |
| Max Amplification | 3.5 % | 2.4 % |

|                 |       |
|-----------------|-------|
| Green Imbalance | 1.2 % |
|-----------------|-------|

Vignetting Measurement done with an integrating sphere with illuminant D50

**Results:** Good vignetting and color lens shading performance

**• Measurement conditions:**

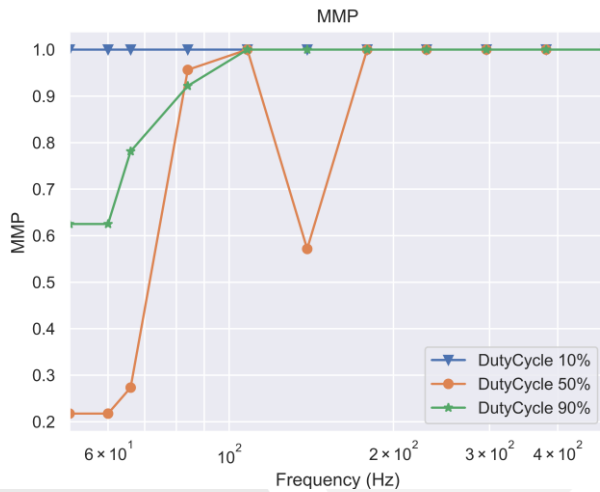
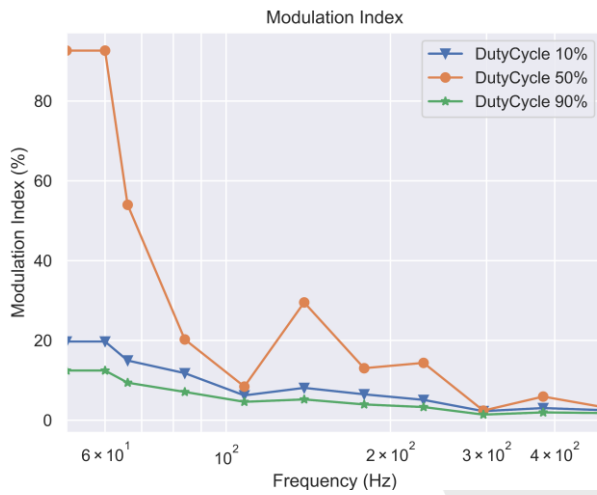
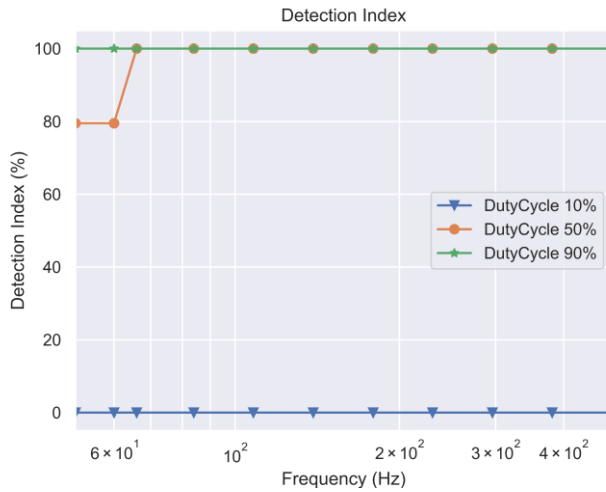
- 16 LED PWM frequencies in Hz: 50, 51, 60, 66, 84, 108, 139, 150, 179, 200, 230, 296, 300, 381, 490, 1000
- 3 LED PWM duty cycles: 10%, 50%, 90%
- 3 test conditions:
  - Background at 10000 lux, LED light intensity at 3000 cd/m<sup>2</sup>
  - Background at 180 lux, LED light intensity at 90 cd/m<sup>2</sup>
  - Background at 0.5 lux, LED light intensity at 6 cd/m<sup>2</sup>

**• Results:**

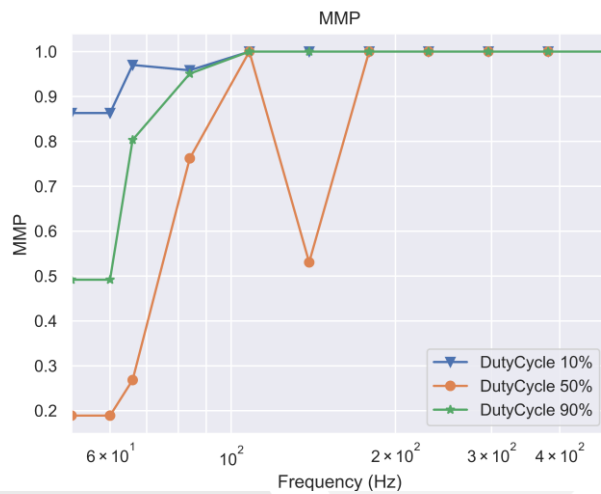
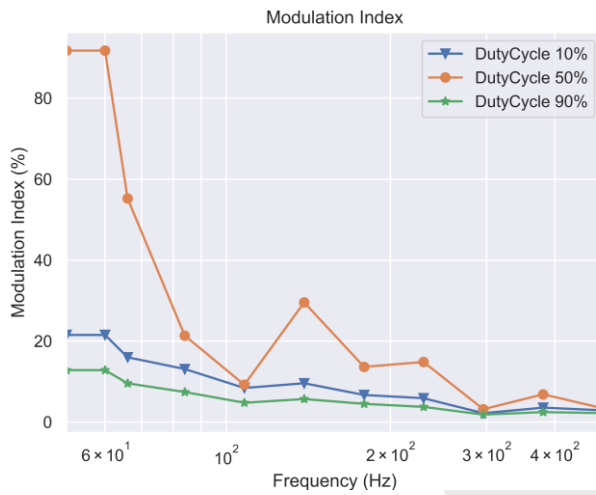
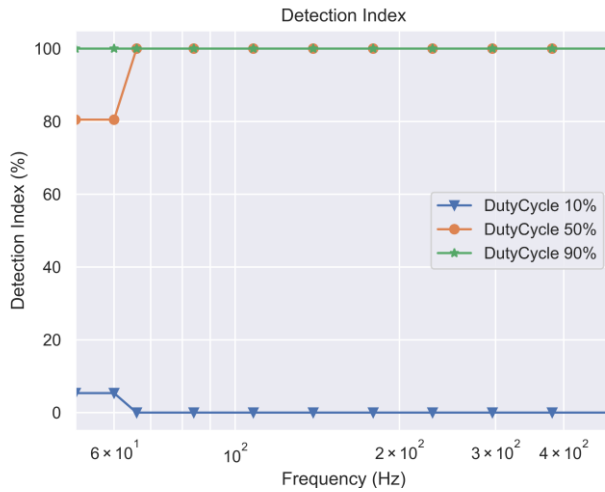
- The exposure time is 10ms:
  - Significant flickering for frequencies below 100Hz (1 / exposure time)
  - Limited flickering for high frequencies
- No other visible LED flicker mitigation effect
- The response to flickering is the same for the 3 tested lighting conditions



Background at 10000 lux, LED light at 3000 cd/m<sup>2</sup>



Background at 180 lux, LED light at 90 cd/m<sup>2</sup>



Background at 0.5 lux, LED light at 6 cd/m<sup>2</sup>

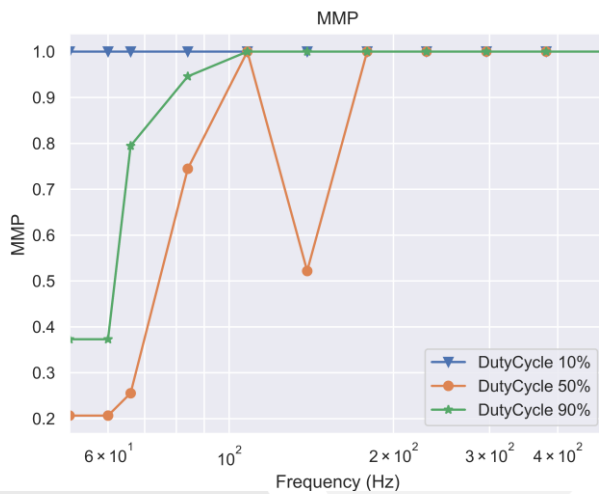
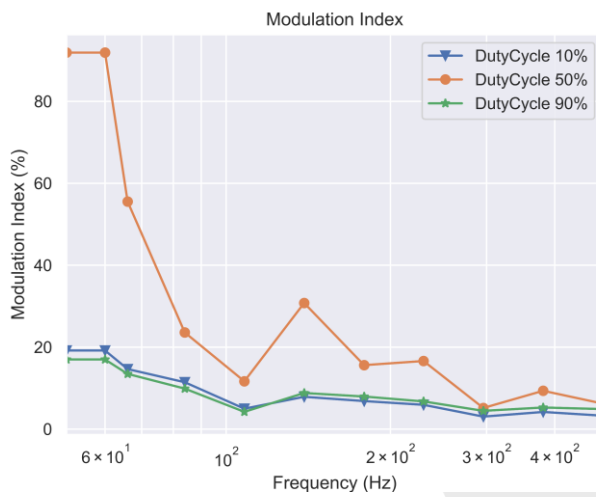
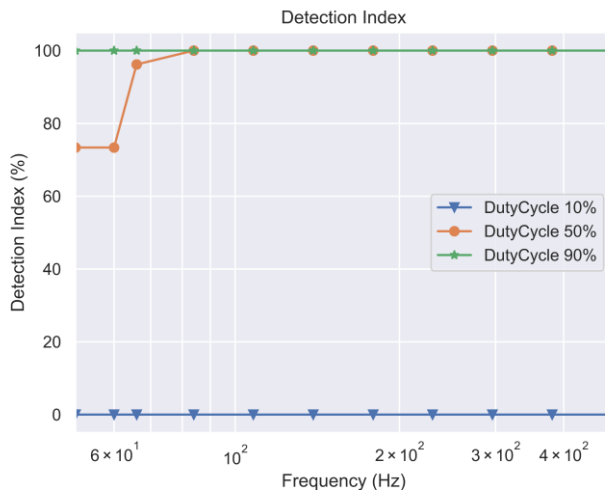
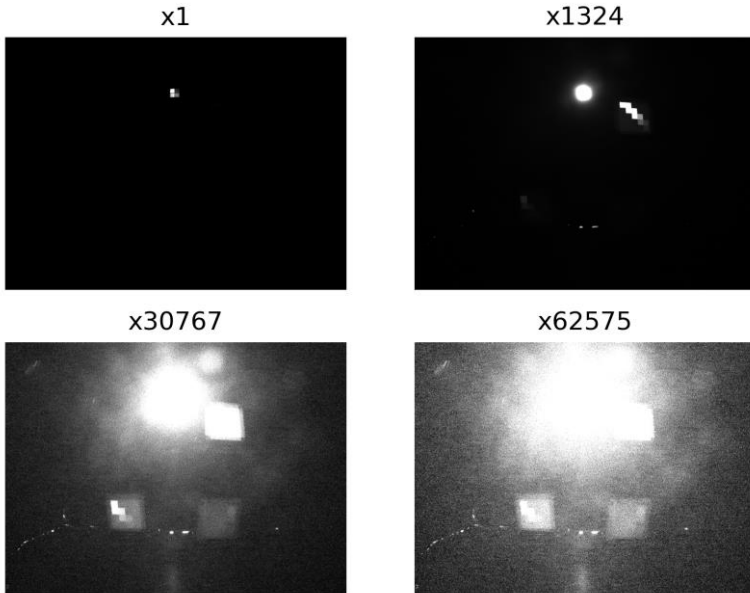
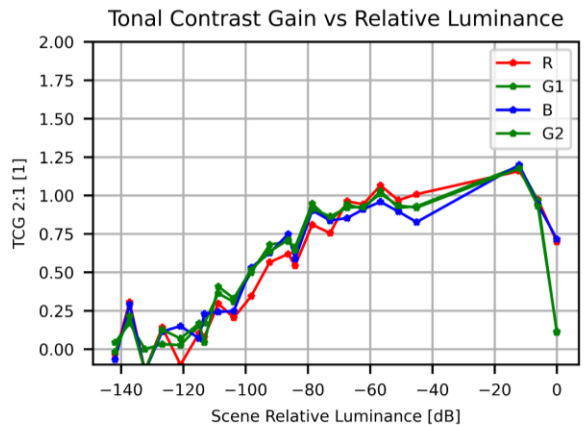
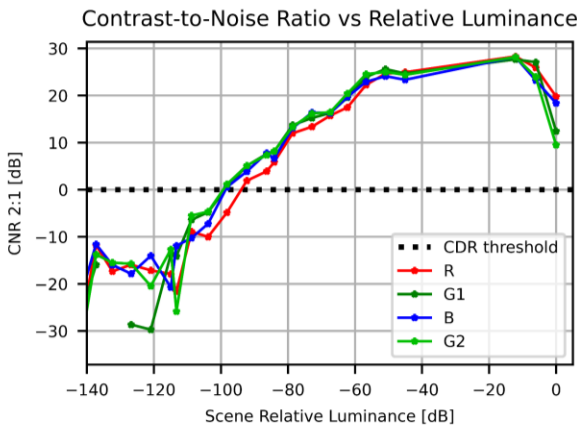
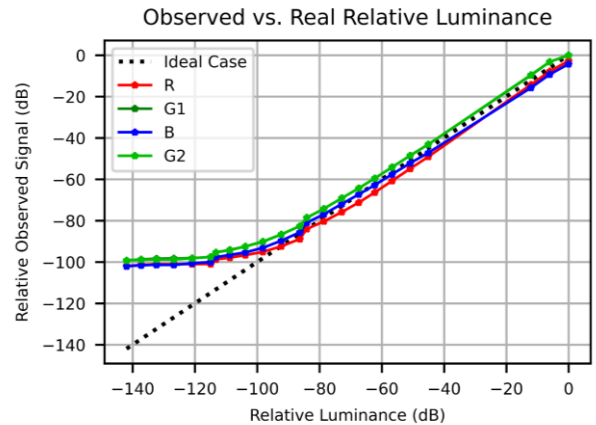


Image preview with different amplification factors



150dB setup with maximum scene luminance 37000 cd/m<sup>2</sup>



|          | R     | G1    | B     | G2     |
|----------|-------|-------|-------|--------|
| CDR (dB) | 94 dB | 99 dB | 99 dB | 100 dB |

The P2020 dynamic range (CDR) value is only 10dB lower than the sensor level dynamic range, which means that the lens is well fitted to the sensor.



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